

Damped SHO:  $\Sigma F = -kx - bv = ma$

quadratic would be more realistic but more difficult

Solve using  $x = e^{rt}$   
 Note: Like Laplace Transform where used  $e^{st}$   
 $\dot{x} = r e^{rt}$   
 $\ddot{x} = r^2 e^{rt}$

$$0 = ma + bv + kx$$

$$0 = \ddot{x} + \frac{b}{m} \dot{x} + \frac{k}{m} x$$

$\underbrace{\frac{b}{m}}_{2\beta} \quad \underbrace{\frac{k}{m}}_{\omega_0^2}$

$$0 = \ddot{x} + 2\beta \dot{x} + \omega_0^2 x$$

$$r = \frac{-2\beta \pm \sqrt{(2\beta)^2 - 4\omega_0^2}}{2}$$

$$0 = (r^2 + 2\beta r + \omega_0^2) e^{rt}$$

quadratic equation

$$= -\beta \pm \sqrt{\beta^2 - \omega_0^2}$$

if  $> 0$  "over damped"  
 if  $< 0$  "under damped"  
 if  $= 0$  "critically damped"

$$r = -\beta \pm i \sqrt{\omega_0^2 - \beta^2}$$

define  $\omega_1$

2 adjustable constants that could be matched with  $x_0$  &  $v_0$

over damped  $x(t) = A e^{r_+ t} + B e^{r_- t}$

these are both negative so expo decay with time

critical damped:  $x(t) = A e^{-\beta t} + B t e^{-\beta t}$

under damped:  $x(t) = [A e^{+i\omega_1 t} + B e^{-i\omega_1 t}] e^{-\beta t}$

$$= [\tilde{A} \cos \omega_1 t + \tilde{B} \sin \omega_1 t] e^{-\beta t}$$

$$= \tilde{\tilde{A}} \cos(\omega_1 t - \delta) e^{-\beta t}$$

equivalent forms all with 2 adjustable constants

The adjustable constants could be expressed in terms of  $x_0$  &  $v_0$  but its a mess.

