

```

Fourier[list]
InverseFourier[list]

N1=256
data = Table[N[Sin[20 2 Pi n/N1]], {n, N1}];  $\leftarrow$  pure sin wave up to 20;  $\frac{256-20}{2}$  negative freq
ListLinePlot[data]
Data=Fourier[data];
ListLinePlot[Abs[Data],PlotRange->All]  $\leftarrow$  see results at 20 &  $\frac{256-20}{2}$ 

data = Table[N[ $\sin(20 \cdot 2 \pi \cdot n/256)$ ] + (RandomReal[] - 1/2)], {n, N1}];  $\leftarrow$  add random noise
ListLinePlot[data]
Data=Fourier[data];
ListLinePlot[Abs[Data],PlotRange->All]  $\leftarrow$  see previous peaks + noise at all frequencies

data = Table[N[Mod[n,20]], {n, N1}];  $\leftarrow$  sawtooth wave - has discontinuity
ListLinePlot[data]
Data=Fourier[data];
ListLinePlot[Abs[Data],PlotRange->All]  $\leftarrow$  lots of strong harmonics due to discontinuity
Data[[1]]  $\leftarrow$  0th harmonic is DC signal; to remove it subtract average
md=Mean[data]
data = Table[N[Mod[n,20]-md], {n, N1}];
ListLinePlot[data]
Data=Fourier[data];
ListLinePlot[Abs[Data],PlotRange->All];
Data[[1]]  $\leftarrow$  now zero

data = Table[Abs[N[Mod[n,40]-20]]-10, {n, N1}];  $\leftarrow$  triangle wave; no discontinuity
ListLinePlot[data]
Data=Fourier[data];
ListLinePlot[Abs[Data],PlotRange->All];  $\leftarrow$  weaker harmonics; Nyquist looks OK

data = Table[N[Mod[n,20]-md], {n, N1}];
data2=Table[Sum[data[[k]],{k,Max[1,i-5],i}]/5,{i,N1}];  $\leftarrow$  running sum of sawtooth
ListLinePlot[data2];
Data2=Fourier[data2];
ListLinePlot[Abs[Data2],PlotRange->All];  $\leftarrow$  reduced high freq harmonics

data = Table[N[ $\sin(20 \cdot 2 \pi \cdot n/256)$ ] + (RandomReal[] - 1/2)], {n, N1};
data2=Table[Sum[data[[k]],{k,Max[1,i-5],i}]/5,{i,N1}];  $\uparrow$  sin wave + noise
ListLinePlot[data2];
ListLinePlot[data];
Data2=Fourier[data2];
ListLinePlot[Abs[Data2],PlotRange->All];  $\leftarrow$  reduced high freq noise
Data=Fourier[data];
ListLinePlot[Abs[Data],PlotRange->All]

```

recursion formula uses results from <http://www-users.cs.york.ac.uk/~fisher/mkfilter/trad.html>  
 for Butterworth, 5th order, corner=1000, sampling=10000  
 note:  $y[ ]$  refers to an entry number in a Table (or array) ...the entry number is a whole number 1 to max  
 $yy[ ]$  is a function of a real (or even complex) number

$y = \text{Table}[0, \{i, 50\}]$  ← Step 1 ⇒  $y$  will be filtered response to step  
 $x[n_] = \text{UnitStep}[n-6]$

```
Do[
y[[n_]] = 1 x[n- 5] + 5 x[n- 4] + 10 x[n- 3] + 10 x[n- 2] + 5 x[n- 1] + 1 x[n- 0] +
  0.1254306222 y[[n- 5]] + -0.8811300754 y[[n- 4]] + 2.5452528683 y[[n- 3]] + -3.8060181193 y[[n- 2]] + 2.9754221097 y[[n- 1]],
{n, 6, 50}]
ListPlot[y, Joined->True, PlotRange->All]
```

↑ digital filter

$w = .5$  ← a freq "passed" by this low pass filter

```
x[n_] = Exp[I w n]
y = Table[0, {i, 100}]
Do[
y[[n_]] = 1 x[n- 5] + 5 x[n- 4] + 10 x[n- 3] + 10 x[n- 2] + 5 x[n- 1] + 1 x[n- 0] +
  0.1254306222 y[[n- 5]] + -0.8811300754 y[[n- 4]] + 2.5452528683 y[[n- 3]] + -3.8060181193 y[[n- 2]] + 2.9754221097 y[[n- 1]],
{n, 6, 100}]
ListPlot[Re[y], Joined->True, PlotRange->All]
```

← see amplified; note "start up"

$w = 1.5$  ← a freq "blocked" by this low pass filter

```
x[n_] = Exp[I w n]
y = Table[0, {i, 60}]
Do[
y[[n_]] = 1 x[n- 5] + 5 x[n- 4] + 10 x[n- 3] + 10 x[n- 2] + 5 x[n- 1] + 1 x[n- 0] +
  0.1254306222 y[[n- 5]] + -0.8811300754 y[[n- 4]] + 2.5452528683 y[[n- 3]] + -3.8060181193 y[[n- 2]] + 2.9754221097 y[[n- 1]],
{n, 6, 60}]
ListPlot[Re[y], Joined->True, PlotRange->All]
```

← much suppressed cf  $w=.5$   
note "start up"

ClearAll[w]

$xx[n_] = \text{Exp}[I w n]$   
 $yy[n_] = \text{Exp}[I w n]$

the amplitude for any freq

```
A[ww_] = (1 xx[- 5] + 5 xx[- 4] + 10 xx[- 3] + 10 xx[- 2] + 5 xx[- 1] + 1 xx[- 0])/
(1 - (0.1254306222 yy[- 5] + -0.8811300754 yy[- 4] + 2.5452528683 yy[- 3] + -3.8060181193 yy[- 2] + 2.9754221097 yy[- 1]))
```

Plot[Abs[A[w]], {w, .01, Pi}]

Show[GraphicsArray[{{%9, %14}, {%, %19}}]]

$w = .5$

ClearAll[x]

$x = \text{Table}[\text{Exp}[I w n] + (\text{RandomReal}[] - 1/2), \{n, 100\}]$ ;

$x[[1]] = 0; x[[2]] = 0; x[[3]] = 0; x[[4]] = 0; x[[5]] = 0$ ;

ListPlot[Re[x], Joined->True, PlotRange->All]

$y = \text{Table}[0, \{i, 100\}]$

Do[

$y[[n_]] = 1 x[[n- 5]] + 5 x[[n- 4]] + 10 x[[n- 3]] + 10 x[[n- 2]] + 5 x[[n- 1]] + 1 x[[n- 0]] +$   
 $0.1254306222 y[[n- 5]] + -0.8811300754 y[[n- 4]] + 2.5452528683 y[[n- 3]] + -3.8060181193 y[[n- 2]] + 2.9754221097 y[[n- 1]],$   
 $\{n, 6, 100\}$

ListPlot[Re[y], Joined->True, PlotRange->All]

↓ passed freq + noise

## Digital Filters

### Finite Impulse Response (non recursive)

response is for  $\rightarrow$  input is zero except at a single time  
a finite time

$$\text{output } y_k = a_0 x_k + a_1 x_{k-1} + a_2 x_{k-2} + \dots + a_n x_{k-n}$$

e.g. "running average" where  $a_i$  are constant  $= \frac{1}{n+1}$

Note: seek response to a unit step + a unit sinusoidal at some freq  $\omega$

### Infinite Impulse Response (recursive)

$$\text{output } y_k = a_0 y_k + a_1 y_{k-1} + \dots + a_n y_{k-n} \\ - (b_1 y_{k-1} + b_2 y_{k-2} + \dots + b_m y_{k-m})$$

Just as a damped driven harmonic oscillator has a homogeneous solution (that decays & depends on initial conditions) and a steady particular solution that does not depend on initial conditions same applies here to digital filters — if  $x_k = e^{i\omega k}$  long term  $y_k = A e^{i\omega k}$  where  $A$  will depend on the frequency.

$$A(e^{i\omega k} + b_1 e^{i(\omega-1)k} + b_2 e^{i(\omega-2)k} + \dots + b_m e^{i(\omega-m)k})$$

$$= a_0 e^{i\omega k} + a_1 e^{i(\omega-1)k} + a_2 e^{i(\omega-2)k} + \dots + a_n e^{i(\omega-n)k}$$

$$\Rightarrow A = \frac{a_0 + a_1 e^{-i\omega} + \dots + a_n e^{-in\omega}}{1 + b_1 e^{-i\omega} + b_2 e^{-2i\omega} + \dots + b_m e^{-m\omega}}$$

so can use above to find amplitude & phase of output.